DeepPositioning: Intelligent Fusion of Pervasive <u>Magnetic Field</u> and <u>WiFi</u> <u>Fingerprinting</u> for Smartphone Indoor Localization via Deep Learning

#### Introduction

#### **Indoor localization**

Example: Guoguo system (use the acoustic signal, accuracy is about 6-25cm).

No widely accepted solutions that can achieve the desired **accuracy** at an acceptable **cost**.

#### Why Wi-Fi?

- Low complexity
- Real-time online process

CSI (Channel State Information): provide more information of the channel. need specific WiFi network interface cards

#### Why Magnetic Field?

- Static
- Have sufficient local variability

Disadvantage:

• The values of magnetic field are different between two phone.

#### WiFi & Magnetic Field

Example: Magicol system designed a two-pass bidirectional particle filtering process.

DeepPosition: use deep learning method

traditional solutions: filtering, manual data analysis, time-consuming parameter tuning

## RSS measurements

- a smartphone
- performed in a room, 13.4m×6.4m
- selected 120 reference locations
- The average distance between adjacent reference points is 0.6 m in both X and Y axis
- 120-130 fingerprint samples at each RP and the measurement lasts for 5 minutes
- RSSI data collected from 242 different APs with unknown locations are used
- lack of signal strength measurement is set to -110 dBm

#### Magnetic measurements

- convert to coordinates with respect to the world coordinate system
- chose the two values of y and z coordinates as part of fingerprint sample
- The fingerprinting consist of signal strengths from 242 APs, and y and z magnetic values in fixed world basis

#### Dataset

- DS1- the training set includes all of 120 RPs and testing set includes 20 extra positions that were randomly selected
- DS2- 120 RPs are divided into 88 training positions and 32 test positions

| Dataset | Training Set | Testing Set |
|---------|--------------|-------------|
| DS-1    | 120          | 20          |
| DS-2    | 88           | 32          |

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| fect of the |         |                              | еер ти            |
| etworks     |         |                              |                   |
| TABLE II    | I. Mean | Absolute Error for D<br>DS-1 | ifferent DNNs wit |
|             | DNN     | Mean Error (m)               | Std. Dev. (m)     |
|             | х       | 1.1035                       | 1.0484            |
| 4- reg      | Y       | 0.7487                       | 0.6483            |
|             | Dis.    | 1.4551                       | 1.0866            |
|             | х       | 1.3455                       | 0.9540            |
| 4-aut-reg   | y Y     | 0.8670                       | 0.6480            |
|             | Dis.    | 1.7270                       | 0.9537            |
|             | х       | 1.2040                       | 1.1588            |
| 4- cls      | Y       | 1.1165                       | 0.8701            |
|             | Dis.    | 1.8846                       | 1.1153            |
|             | x       | 1.1857                       | 0.9282            |
| 3-reg       | Y       | 1.2192                       | 0.7850            |
|             | Dis.    | 1.9442                       | 0.9185            |

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|----------|-------|-------------------|------------------------------|-------------------|------------------|
| TABL     | E IV. |                   | lute Error f<br>fferent Dat. | FOR DEEPPOSIT     | TIONING WI       |
|          |       | DS                | 8-1                          | DS-2              |                  |
|          |       | Mean<br>error (m) | Std. dev.<br>(m)             | Mean<br>error (m) | Std. dev.<br>(m) |
|          | х     | 1.1035            | 1.0484                       | 1.3816            | 1.1969           |
| 4-reg    | Y     | 0.7487            | 0.6483                       | 0.7925            | 0.6532           |
|          | Dis.  | 1.4551            | 1.0866                       | 1.7172            | 1.2030           |
| 4-       | Х     | 1.3455            | 0.9540                       | 1.2483            | 1.1338           |
| aut-     | Υ     | 0.8670            | 0.6480                       | 1.0653            | 0.8384           |
| reg      | Dis.  | 1.7270            | 0.9537                       | 1.9977            | 1.0546           |

# Effect of the Fusion of Magnetic Field and WiFi

|                               |      | Mean Error (m) | Std. Dev. (m) |
|-------------------------------|------|----------------|---------------|
| DeepPos<br>itioning<br>(DS-1) | x    | 1.1035         | 1.0484        |
|                               | Y    | 0.7487         | 0.6483        |
|                               | Dis. | 1.4551         | 1.0866        |
| wifi-<br>only<br>(DS-1)       | x    | 1.6566         | 1.1139        |
|                               | Y    | 1.0186         | 0.6923        |
|                               | Dis. | 2.1742         | 0.9271        |
| wifi-<br>only<br>(DS-2)       | х    | 1.8838         | 1.2800        |
|                               | Y    | 1.1687         | 0.8101        |
|                               | Dis. | 2.3878         | 1.2279        |

| TABLE V. | MEAN ABSOLUTE ERROR FOR DEEPPOSITIONING AND |
|----------|---|
|          | WIFI-ONLY                                   |

### Advantages

|                               |      | Mean Error (m) | Std. Dev. (m) |
|-------------------------------|------|----------------|---------------|
| DeepPos<br>itioning<br>(DS-1) | х    | 1.1035         | 1.0484        |
|                               | Y    | 0.7487         | 0.6483        |
|                               | Dis. | 1.4551         | 1.0866        |
| wifi-<br>only<br>(DS-1)       | х    | 1.6566         | 1.1139        |
|                               | Y    | 1.0186         | 0.6923        |
|                               | Dis. | 2.1742         | 0.9271        |
| wifi-<br>only<br>(DS-2)       | Х    | 1.8838         | 1.2800        |
|                               | Y    | 1.1687         | 0.8101        |
|                               | Dis. | 2.3878         | 1.2279        |

DeepPositioning proposed in this paper achieves a 30% improvement over the WIFI-only case.

#### Drawbacks

- 1. Only use one phone to collect data
- 2. Depends on the number of Aps, RPs, and labeled samples in training dagtasets.

#### What we did in last week

- Solving the main problem: The dataset to use CNN
- Some ideas:
- 1. One channel for RSSI, one channel for Geo-magnetic Each row for each place.
- 2. Filtering a series of RSSI that affect most, concatenate to position.
- 3. Collect RSSI at one position in different orientations, in order to improve the accuracy using magnetic.

